
atled Documentation

Release <https://github.com/vroncevic/atled/releases/>

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4legs is variant of legged robot.

4legs is developed in C code: **100%**.

The README is used to introduce the tool and provide instructions on how to install the tool, any machine dependencies it may have and any other information that should be provided before the tool is installed.

INSTALLATION



```
_,met$$$$$gg.  
,g$$$$$$$$$$$$$P.  
,g$$P"        ""Y$$.  
,$$P'          $$$.  
,,$$P        ,ggs.    $$b:  
`d$$'        ,P"      $$$  
$$P          d$'      $$P  
$$:          $$      ,d$$'  
$$;          Y$b._    ,dP'  
Y$$          ``"Y$$$$P"  
`$$b        "-._  
`Y$$  
`Y$$.  
`$$b.  
`Y$$b.  
  "Y$b._  
    ""
```

```
vroncevic@debtux  
-----  
OS: Debian GNU/Linux 11 (bullseye) x86_64  
Host: 20F5S80B00 ThinkPad X260  
Kernel: 5.10.0-8-amd64  
Uptime: 34 mins  
Packages: 3372 (dpkg)  
Shell: bash 5.1.8  
Resolution: 1366x768  
DE: GNOME 3.38.4  
WM: Mutter  
WM Theme: Adwaita  
Theme: Adwaita-dark [GTK2/3]  
Icons: Adwaita [GTK2/3]  
Terminal: terminator  
CPU: Intel i5-6200U (4) @ 2.800GHz  
GPU: Intel Skylake GT2 [HD Graphics 520]  
Memory: 2907MiB / 7390MiB
```



Navigate to release [page](#) download and extract release archive.

To install **4legs** type the following

```
in progress
```


DEPENDENCIES

4legs requires next modules and libraries in progress

PROJECT STRUCTURE

4legs is based on POP.

in progress

COPYRIGHT AND LICENCE

Copyright (C) 2020 by dof2bot.github.io/4legs